

# Serial Master HOW-TO

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## 1. About

This document is a tutorial for writing Modbus/Serial Master applications utilizing the *jamod* library. It explains the basics and walk's you through a simple command line Master implementation, that will allow you to read the state of one or more input registers from a slave on the network.

If you are new to Modbus, it is highly recommended to first take a look at "[Understanding the Protocol](#)" (`./kbase/protocol.html`) (especially the section about the Serial implementation) as well as the actual protocol specifications.

### Warning:

You will need an implementation of the Java Communications API extension (`javax.comm`) installed to be able to run serial modbus applications.

Note that there is also support for building with the `gnu.io` prefix (RXTX), via the *boolean* build property `build.serial.gnu` (`true` will cause the build process to replace the `javax.comm` prefix with `gnu.io` in the sources used for builds).

### Note:

The application build in the tutorial is actually part of the distribution codebase ([net.wimpi.modbus.cmd.SerialAITest](#) (`./api/net/wimpi/modbus/cmd/SerialAITest.html`)).

## 2. What is a Master?

Thinking in terms of the Client-Server network computing paradigm, the Master application is a **client**. It establishes a *connection* with the slave (i.e. the **server**) and uses this connection for sending a *Request* to the slave, from which a *Response* will be received.

As described in [Understanding the Protocol](#) (`./kbase/protocol.html`), each cycle of *Request* and *Response* is called a *Transaction*. Figure 1 shows a simple graphical representation of such a cycle:

Modbus Transaction

**Table 1: Figure 1: Modbus Transaction**

In case of the serial implementation, the communication can be point-to-point (RS232, 422, 485) or on a shared signal cable (RS 485). In both cases there should be only one master, that acquires data from a source (data acquisition), or writes data to a sink (device control).

A possible simple "network setup" for this tutorial is composed of two nodes, as depicted in Figure 2.

Network setup

**Table 2: Figure 2: Network Setup**

### 3. What is an Input Register?

According to the Modbus data model, which is part of the protocol specification (see section 4.3), an *Input Register* is a 16 bit word "data item", which is usually provided by an I/O system (analog input module). Figure 3 shows an example with simple switches that are mapped into the slave's process image in form of discrete inputs. The example master application will be capable of obtaining the state of these DI's from the slave.

Slave with IR's

**Table 1: Figure 3: Slave with IR's**

**Note:**

Related information is available in [Understanding the Process Image](#) (processimage.html) .

### 4. Classes of Interest for the Developer

The motivation for creating *jamod* was to achieve an intuitive and object oriented implementation of the protocol, in a way, that there is a natural mapping from the domain knowledge (i.e. Modbus protocol) to the abstract class model. The important elements in the description above (What is a Master?) have been highlighted and the following list represents the mapping between them and the classes from *jamod* that will be needed for a master implementation:

- *Connection*: [SerialConnection](#) (./api/net/wimpi/modbus/net/SerialConnection.html)
- *Transaction*: [ModbusSerialTransaction](#) (./api/net/wimpi/modbus/io/ModbusSerialTransaction.html)
- *Request*: [ModbusRequest](#) (./api/net/wimpi/modbus/msg/ModbusRequest.html) (respectively it's direct known subclass [ReadInputRegistersRequest](#) (./api/net/wimpi/modbus/msg/ReadInputRegistersRequest.html) )
- *Response*: [ModbusResponse](#) (./api/net/wimpi/modbus/msg/ModbusResponse.html) (respectively it's direct known subclass [ReadInputRegistersResponse](#) (./api/net/wimpi/modbus/msg/ReadInputRegistersResponse.html) )
- *Parameters*: [SerialParameters](#) (./api/net/wimpi/modbus/util/SerialParameters.html)

### 5. Implementation

As the idea is to provide a tutorial in form of a very simple command line example, it will consist of only one class and most of the work will be done in the entry method (`public static void main(String args[])`). This is probably not the way *jamod* will be

usually employed in OO designs, but we hope it serves the demonstrative purpose.

Before we start with coding, let's take a look at the simplified interaction diagram of the application, given as Figure 4. The part most interesting for this tutorial is colored blue, but note that the diagram also contains a little bit of the things that happen behind the scenes (i.e. within the Transport, with `writeRequest()` and `readRequest()`), which are there to give a more complete picture.

Sequential Interaction Diagram

**Table 1: Figure 4: Simplified Master Interaction Diagram**

Now let's start writing code. We need a simple Java application skeleton, with imports of all *jamod* packages:

```
import java.net.*;
import java.io.*;
import net.wimpi.modbus.*;
import net.wimpi.modbus.msg.*;
import net.wimpi.modbus.io.*;
import net.wimpi.modbus.net.*;
import net.wimpi.modbus.util.*;

public class SerialAITest {

    public static void main(String[] args) {
        try {
            ...
            ...
        } catch (Exception ex) {
            ex.printStackTrace();
        }
    } //main
} //class SerialAITest
```

Next we add the instances and variables the application will need:

```
/* The important instances of the classes mentioned before */
SerialConnection con = null; //the connection
ModbusSerialTransaction trans = null; //the transaction
ReadInputRegistersRequest req = null; //the request
ReadInputRegistersResponse res = null; //the response

/* Variables for storing the parameters */
String portname = null; //the name of the serial port to be used
int unitid = 0; //the unit identifier we will be talking to
int ref = 0; //the reference, where to start reading from
int count = 0; //the count of IR's to read
int repeat = 1; //a loop for repeating the transaction
```

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Next the application needs to read in the parameters:

1. <portname [String]> as String into portname
2. <Unit Address [int8]> as String into unitid
3. <register [int16]> as int into ref
4. <wordcount [int16]> as int into count
5. {<repeat [int]>} as int into repeat, 1 by default (optional)

```
//1. Setup the parameters
if (args.length < 4) {
    System.exit(1);
} else {
    try {
        portname = args[0];
        unitid = Integer.parseInt(args[1]);
        ref = Integer.parseInt(args[2]);
        count = Integer.parseInt(args[3]);
        if (args.length == 5) {
            repeat = Integer.parseInt(args[4]);
        }
    } catch (Exception ex) {
        ex.printStackTrace();
        System.exit(1);
    }
}
```

These will be used subsequently to setup the connection and the request. First, however, we need to set the identifier of the Master on the serial network (in this case to 1), as well as the parameters for the connection:

```
//2. Set master identifier
ModbusCoupler.createModbusCoupler(null);
ModbusCoupler.getReference().setUnitID(1);

//3. Setup serial parameters
SerialParameters params = new SerialParameters();
params.setPortName(portname);
params.setBaudRate(9600);
params.setDataBits(8);
params.setParity("None");
params.setStopbits(1);
params.setEncoding("ascii");
params.setEcho(false);
```

### Note:

You should adapt the serial parameters to your requirements, which you can do hardcoded or by reading in the parameters from the commandline or as properties file. The parameter setting for the serial encoding will be used by the `SerialConnection` instance to instantiate the proper `SerialTransport` instance. In the example we are using the default flavor (`ascii`), which justifies the formerly presented interaction diagram. If you want to use `rtu` or the `bin` flavor, all you need to do is to set them properly as encoding in the

SerialParameter instance.

Once the parameters are prepared, we can open the connection (in this case the serial port will be opened) as well as prepare a request and a transaction:

```
//4. Open the connection
con = new SerialConnection(params);
con.open();

//5. Prepare a request
req = new ReadInputRegistersRequest(ref, count);
req.setUnitID(unitid);
req.setHeadless();

//6. Prepare a transaction
trans = new ModbusSerialTransaction(con);
trans.setRequest(req);
```

Now we are ready for action. The last part is executing the prepared transaction the given (repeat) number of times and then for cleanup, close the connection:

```
//7. Execute the transaction repeat times
int k = 0;
do {
    trans.execute();
    res = (ReadInputRegistersResponse) trans.getResponse();
    for (int n = 0; n < res.getWordCount(); n++) {
        System.out.println("Word " + n + "=" + res.getRegisterValue(n));
    }
    k++;
} while (k < repeat);

//8. Close the connection
con.close();
```

That's it. This should do the job if the serial connection is established and the parameters are set accordingly for Master and Slave.

### Note:

The debug outputs of the library can be activated by passing the property `net.wimpi.modbus.debug` to the JVM (i.e. `java -Dnet.wimpi.modbus.debug=true`) and allow to see the actually exchanged modbus messages encoded as hex.